Deep learning

11.4. Model persistence and checkpoints

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The underlying operation is **serialization**, that is the transcription of an arbitrary object into a sequence of bytes [that can be saved to disk].

The main PyTorch methods for serializing are torch.save(obj, filename) and torch.load(filename).

```
>>> x = 34
>>> torch.save(x, 'x.pth')
>>> y = torch.load('x.pth')
>>> y
34
```

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One can save directly a full model like this, including arbitrary fields

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Additionally

- Tensors are saved with their locations (CPU, or GPU), and will be loaded in the same configuration,
- in your Modules, buffers have to be identified with register_buffer,
- · loaded models are in train mode by default,
- optimizers have a state too (momentum, Adam).

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A checkpoint is a persistent object that keeps the global state of the training: model and optimizer. In the following example (1) we load it when we start if it exists, and (2) we save it at every epoch.

```
nb_epochs_finished = 0
model = Net()
optimizer = torch.optim.SGD(model.parameters(), lr = lr)
checkpoint_name = 'checkpoint.pth'
try:
    checkpoint = torch.load(checkpoint_name)
    nb_epochs_finished = checkpoint['nb_epochs_finished']
    model.load state dict(checkpoint['model state'])
    optimizer.load_state_dict(checkpoint['optimizer_state'])
    print(f'Checkpoint loaded with {nb epochs finished} epochs finished.')
except FileNotFoundError:
    print('Starting from scratch.')
except:
    print('Error when loading the checkpoint.')
    exit(1)
```

```
for k in range(nb_epochs_finished, nb_epochs):
    acc loss = 0
    for input, targets in zip(train_input.split(batch_size),
                              train_targets.split(batch_size)):
        output = model(input)
        loss = criterion(output, targets)
        acc loss += loss.item()
        optimizer.zero_grad()
        loss.backward()
        optimizer.step()
    print(k, acc_loss)
    checkpoint = {
        'nb epochs finished': k + 1.
        'model_state': model.state_dict(),
        'optimizer_state': optimizer.state_dict()
    }
    torch.save(checkpoint, checkpoint_name)
```

```
If we killall python during training
```

```
fleuret@elk:/tmp/ ./tinywithcheckpoint.py
Starting from scratch.
0 161.2404215920251
1 35.50377965264488
2 24.43254833246465
3 18.57419647696952
4 14.582882737944601
Killed
```

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Killed
```

and re-start

```
fleuret@elk:/tmp/ ./tinywithcheckpoint.py
Checkpoint loaded with 5 epochs finished.
5 11.396404800716482
6 8.944935847055604
7 7.116929043420896
8 5.463898817846712
9 4.41012461569494
test_error 1.01% (101/10000)
```



Since a model is saved with information about the CPU/GPUs where each **Storage** is located there may be issues if the model is loaded on a different hardware configuration.

For instance, if we save a model located on a GPU:

```
>>> x = torch.nn.Linear(10, 4)
>>> x.to('cuda')
Linear(in_features=10, out_features=4, bias=True)
>>> torch.save(x, 'x.pth')
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```

and load it on a machine without GPU:

```
>>> x = torch.load('x.pth')
Traceback (most recent call last):
/.../
RuntimeError: Attempting to deserialize object on a CUDA device but
torch.cuda.is_available() is False. If you are running on a CPU-only
machine, please use torch.load with map_location=torch.device('cpu')
to map your storages to the CPU.
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This can be fixed by specifying at load time how to relocate storages:

```
>>> x = torch.load('x.pth', map_location = 'cpu')
Linear(in_features=10, out_features=4, bias=True)
```

The end